

Domain Decomposition and Parallel Direct Solvers as an Adaptive Multiscale Strategy for Damage Simulation in Materials

F.P.X. Everdij, O. Lloberas-Valls, A. Simone, D.J. Rixen^{*}, L.J. Sluijs

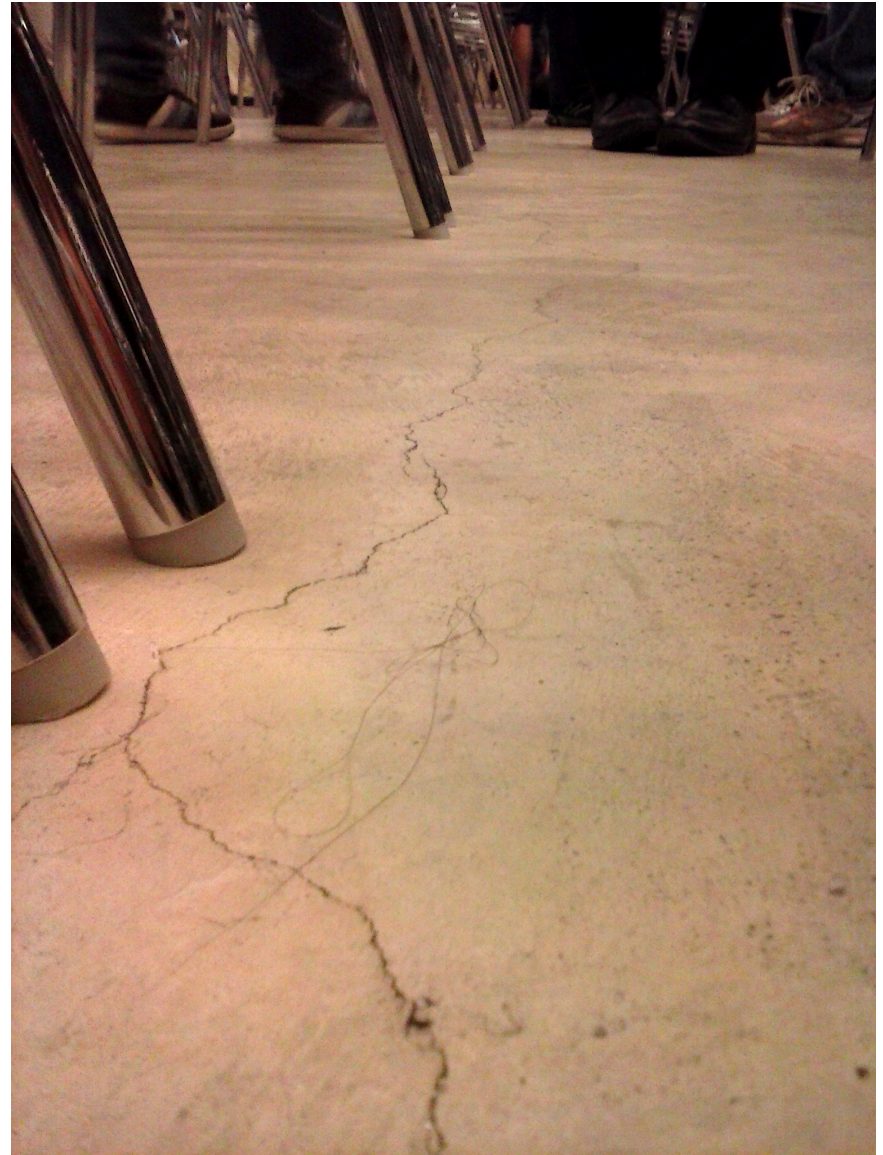
Faculty of Civil Engineering and Geosciences
Delft University of Technology, The Netherlands

^{*} Institute of Applied Mechanics
Technische Universität München

Goal

Numerical model of damage
in heterogeneous materials
→ fracturing in concrete

- Simulate material damage
 - Realistic
 - Efficient
 - Robust
- Damage model properties
 - Mesh objectivity
 - Usable in standard FEM

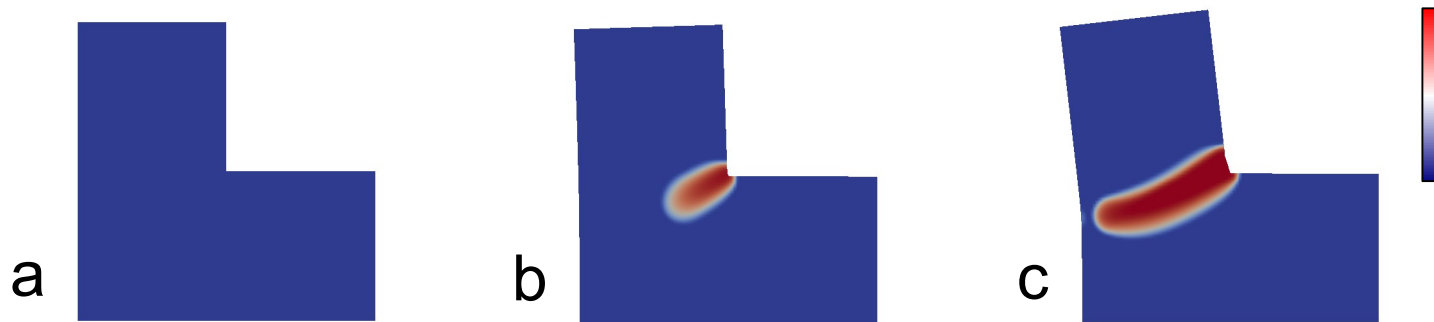
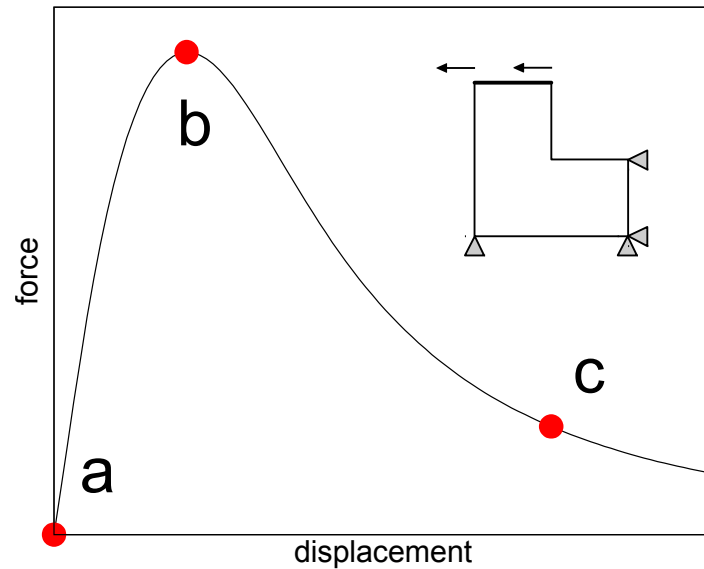


Gradient Enhanced Damage Model

Peerlings et al. (1995)

- Extra dof, drives damage
- Damage scalar ω :

$$D \rightarrow D(1 - \omega)$$



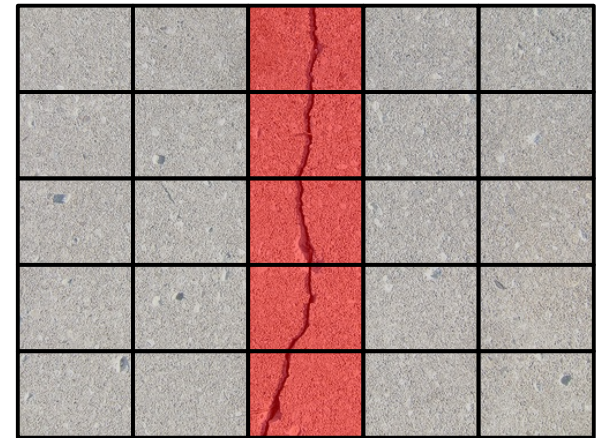
Challenges

- Highly non-linear: requires iterations within increments
- Stiffness matrix is asymmetric
 - Solvers:
 - Umfpack (serial)
 - Pardiso, PaStiX, MUMPS (parallel)
- Crack localization necessitates fine mesh
 - Full numerical solution is expensive

Proposed framework

Multiscale Domain Decomposition

- Subdivide into domains
→ Only part of material needs to have detailed mesh
- Start out with all coarse mesh
- Perform mesh refinement, driven by criteria coupled with damage parameter
- Solver available → FETI



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FETI (classic)

- Decomposition:
 - Lagrange multipliers for boundary conditions
Singular Stiffness matrix
 - Non-conforming meshes → LMP constraints
- Solver for Interface problem:
 - (Direct)
 - Iterative → BiCGStab
 - Preconditioning (SuperLumped, Lumped, Dirichlet)
 - Scaling (m,k,s)

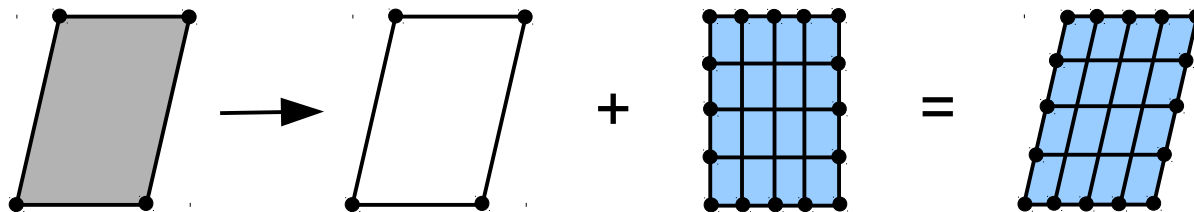
$$K \cdot u = f$$



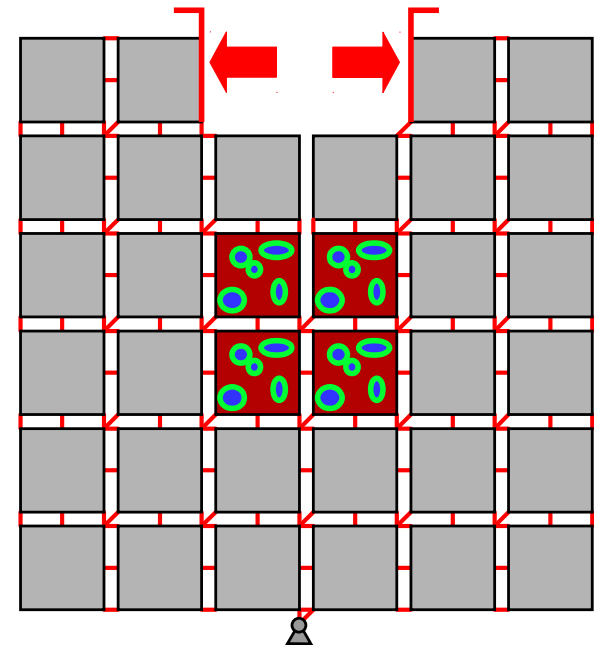
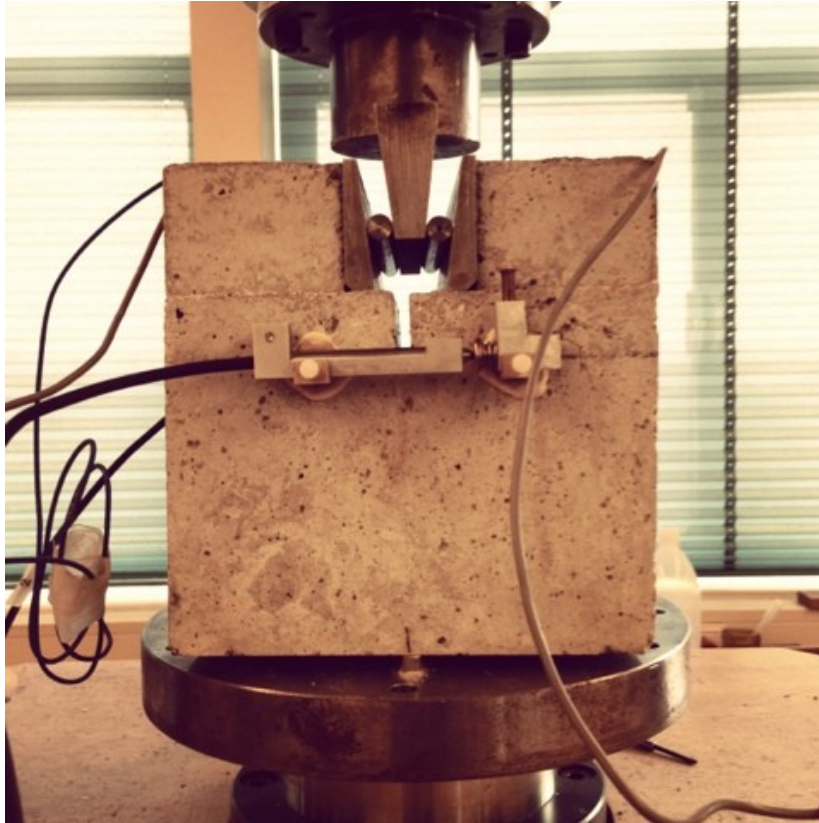
$$\begin{bmatrix} K & B^T \\ B & 0 \end{bmatrix} \begin{bmatrix} u \\ \lambda \end{bmatrix} = \begin{bmatrix} f \\ 0 \end{bmatrix}$$

Multiscale \rightarrow Domain Refinement

- Decide when and where to refine
 - Depends on model
 - Heuristic \rightarrow User defined criteria
- Solve Boundary Value Problem



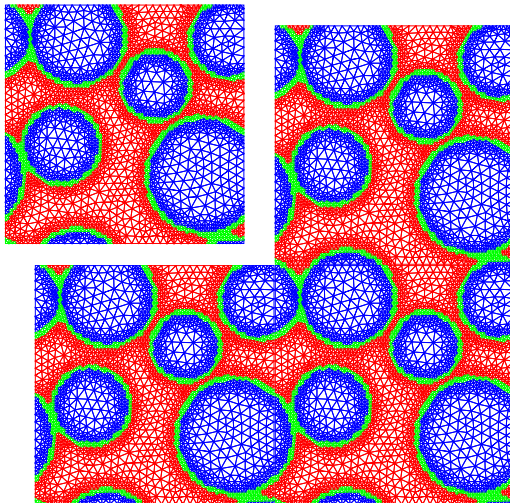
Model Wedge Split test



RVE and Domain

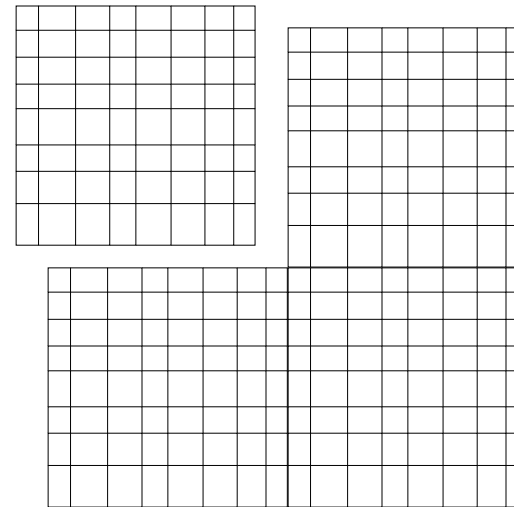
Meso (“fine”)

- Heterogeneous
- Matrix | ITZ | Aggregate
- T3 1ip 11747n 23112e



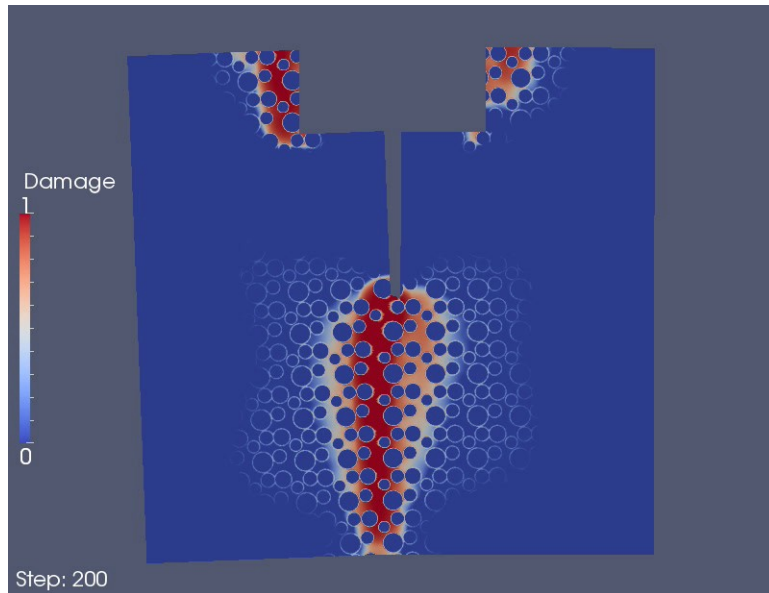
Macro (“coarse”)

- Homogeneous
- D_{eff}
- Q4 4ip 289n 256e

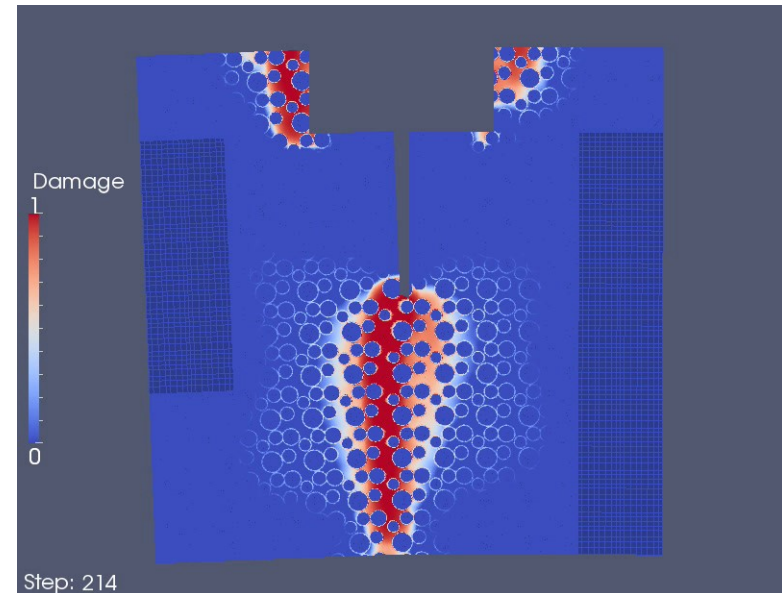


Numerical Results

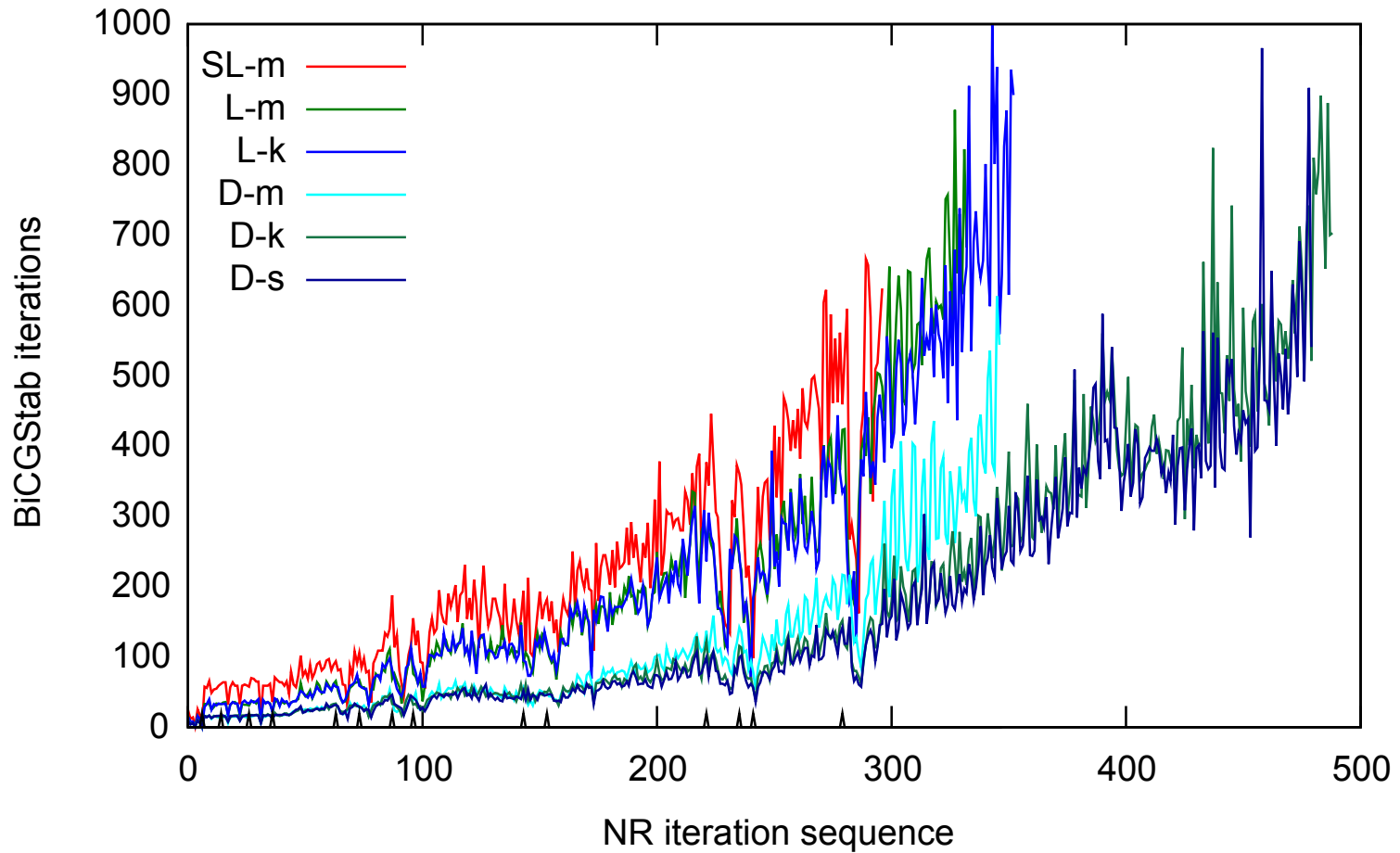
- FNS (Umfpack: 24.5 hours)



- DD 34 (FETI Direct: 59.2 hours)



FETI iterative solver



Problem

- BiCGStab solver takes many iterations to converge
 - Standard preconditioners are not good enough
- Possible causes:
 - Stiffness scaling (k/s) on non-stiffness components

$$\begin{bmatrix} K^{uu} & K^{ue} \\ K^{eu} & K^{ee} \end{bmatrix} \cdot \begin{bmatrix} \delta u \\ \delta u_e \end{bmatrix} = RHS$$

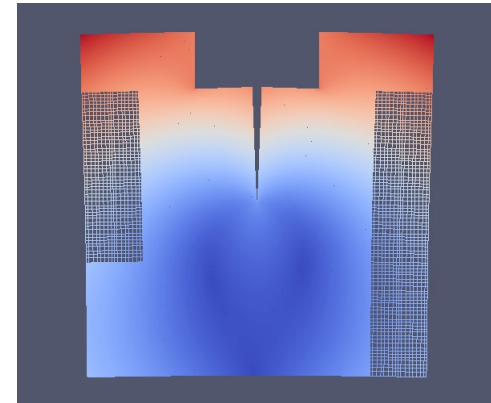
- Damage induced heterogeneity

Damage induced Heterogeneity

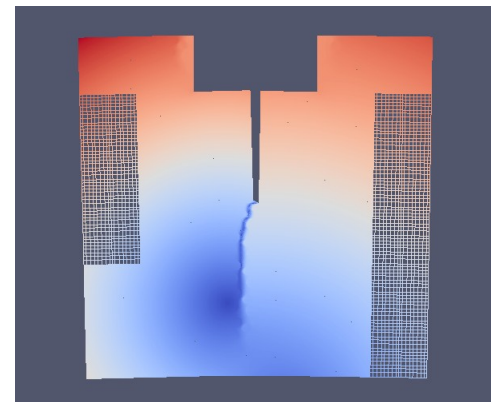
- Linear elastic test on final refined mesh + iterative solver
 - Replace $\mathbf{D} \rightarrow \mathbf{D}(1 - \omega)$
 - Choose different damage profiles

	First Iter L-k	First Iter D-k
ω_0	39	16
ω_{100}	781	233
ω_{214}	>5000	1936

Damage induced heterogeneity indeed causes poor convergence



ω_0



ω_{100}

Possible Solution

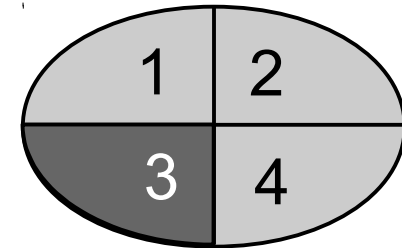
- Eigenvalue methods:
 - local generalized eigenvalue problems
 - FETI-GenEO (Spillane & Rixen, 2013)
→ some adaptation needed

- Idea: Can we combine direct solver robustness with multiscale decomposition?

Yes, via the full Dual assembly

Multiscale → Full Dual assembly

$$\begin{bmatrix} K & B^T \\ B & 0 \end{bmatrix} \begin{bmatrix} u \\ \lambda \end{bmatrix} = \begin{bmatrix} f \\ 0 \end{bmatrix}$$



K_1					B_1^T		u_1	f_1
	K_2				B_2^T		u_2	f_2
		K_3				B_3^T	u_3	f_3
				K_4	B_4^T		u_4	f_4
B_1	B_2	B_3			B_4	0	λ	0

\ast

u_1
u_2
u_3
u_4
λ

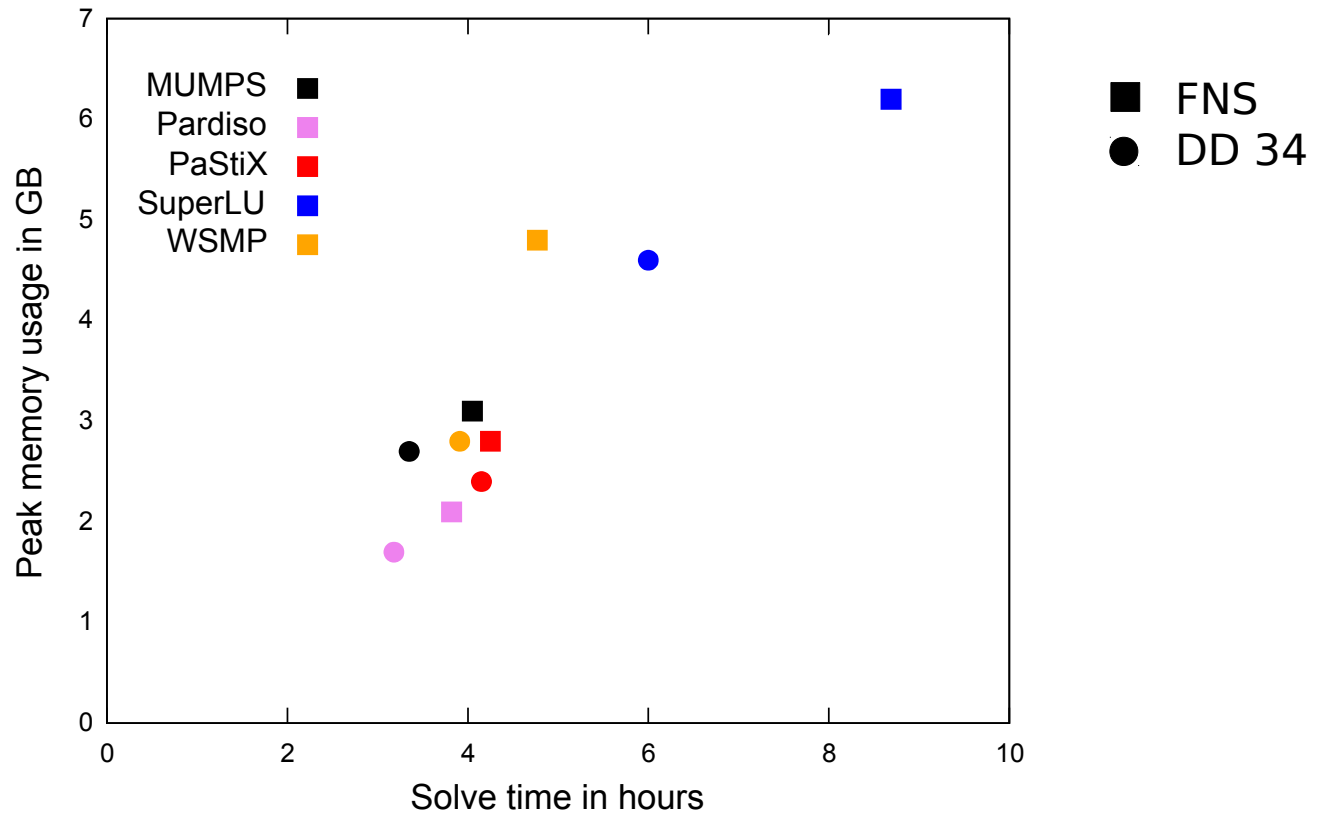
 $=$

f_1
f_2
f_3
f_4
0

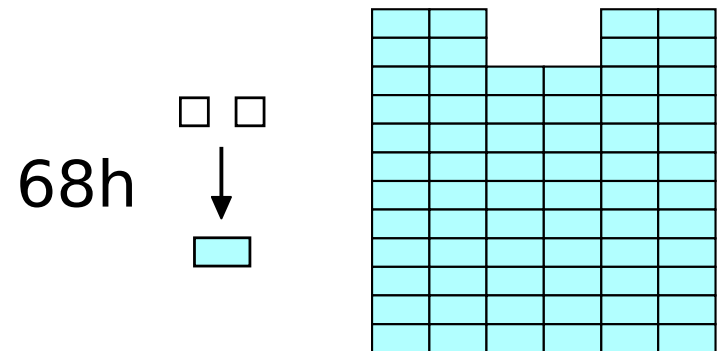
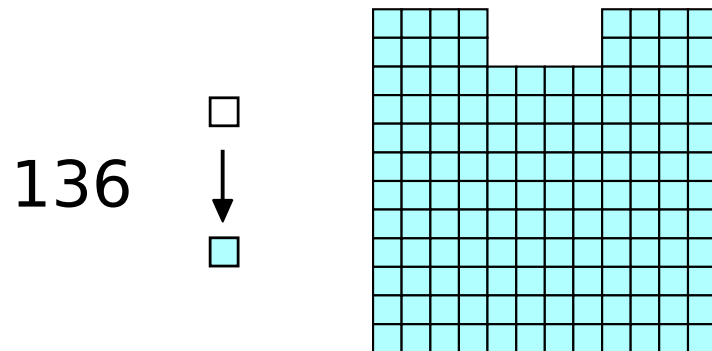
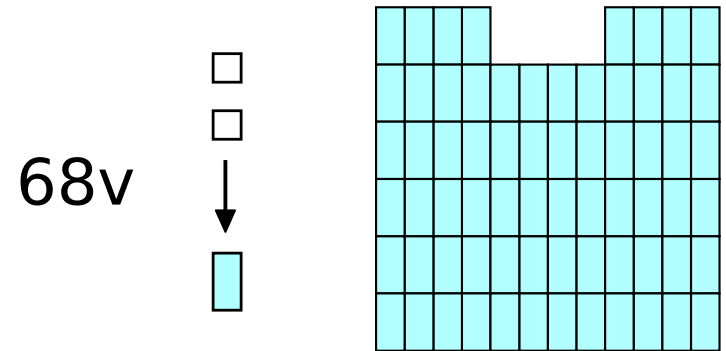
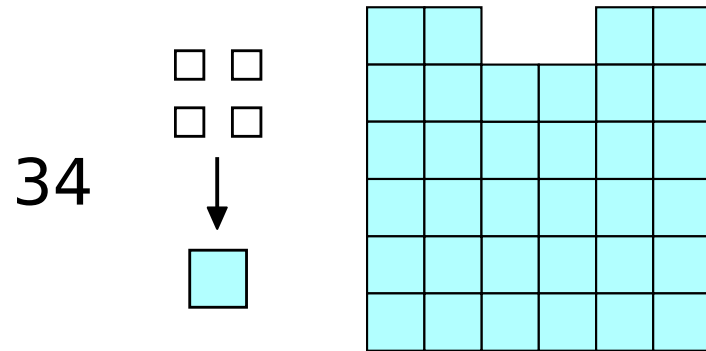
Parallel direct solver + Multiscale + Full Dual assembly

- Less dof's than FNS
 - Majority of domains are coarse “macro” domains
 - Domain refinement induced only by damage growth
- Indifferent of material model
- Examples of parallel direct unsymmetric solvers:
 - MUMPS (4.10.0)
 - Pardiso (4.12)
 - PaStiX (5.2.1-4030)
 - SuperLU (2.1)
 - WSMP (13.106.10)

Results – memory use, run times

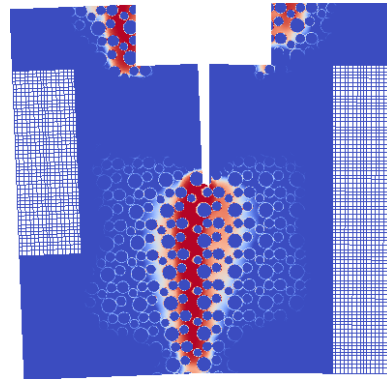


Domain shapes

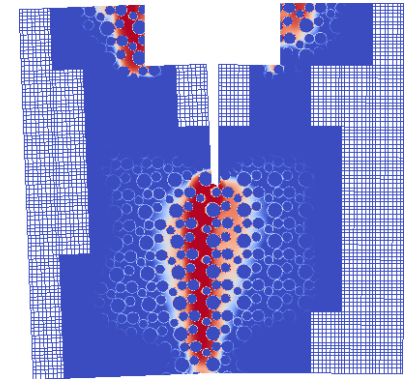


Effect of shape on runtime

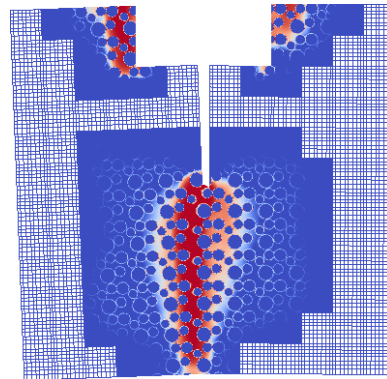
34
4h18m



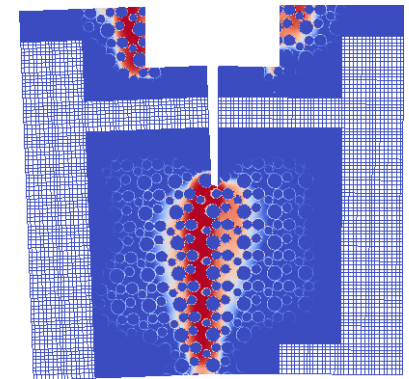
68v
3h45m



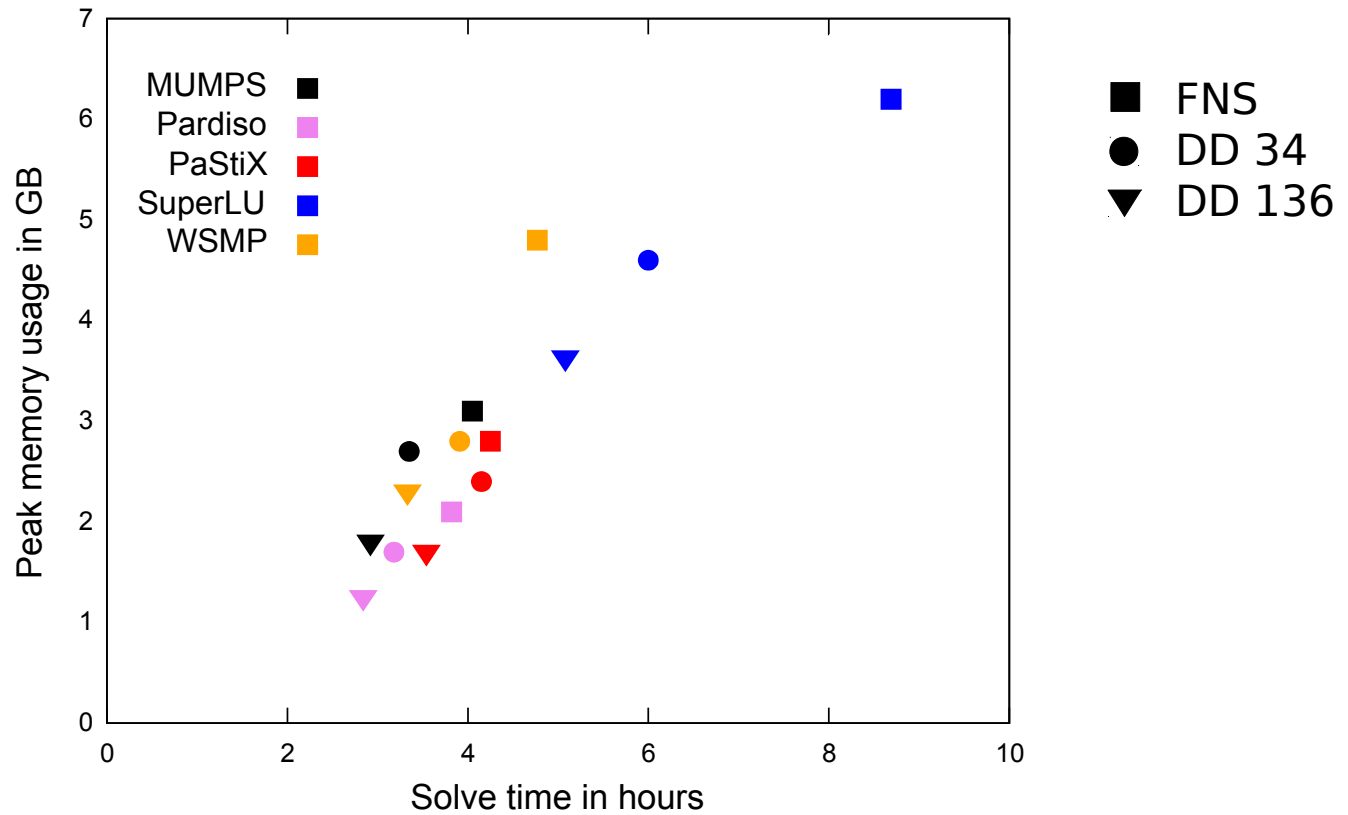
136
3h32m



68h
3h29m



Latest results



Conclusions

- Multiscale framework and parallel direct solver is efficient and robust for damage simulation.
- GEDM needs advanced preconditioners in FETI methods.